## ST. FRANCIS XAVIER UNIVERSITY Constraint Processing and Heuristic Search

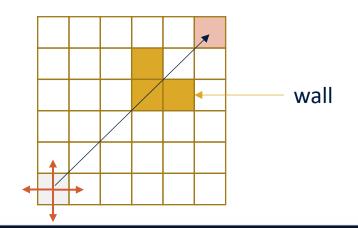
MQUESI

Lecture 7 – Automatically Created Heuristics



### **Automatically Created Heuristics**

- Where do heuristics come from?
  - Heuristics are a relaxations of constraints of the problem.
  - Solves the relaxed problem exactly.
- Example:
  - Straight-line distance estimate for shortest-path.





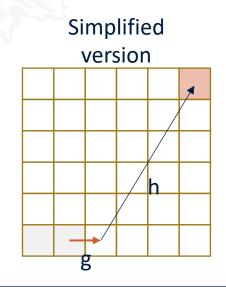
### **Automatically Created Heuristics**

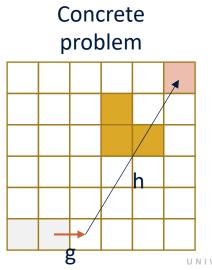
- Heuristics are relaxations of constraints.
  - It's not a directly implementable concept.
- Therefore, we will speak about abstraction transformation.
  - Make automated generation of heuristics possible.
- It's different from hand-craft, domain-dependent solutions.





- The original problem is referred as the concrete problem (or concrete state space).
- The abstraction simplifies the concrete problem.
- The distances/cost in the simplified version are used as heuristic estimates.







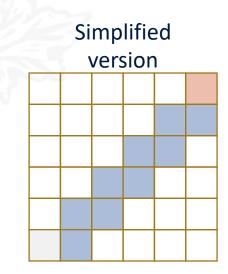
- Note: Combining several heuristics based on different abstractions leads to better estimates.
  - You can create a hierarchy of abstractions.
- The main purpose of abstraction is to reduce the state space.
  - State spaces can be very large, even infinite (continuous state space).
  - You want to reduce the search effort.
- The abstract state space is often smaller.

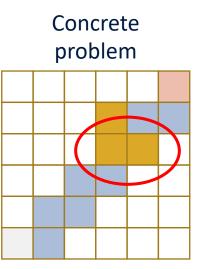
If the abstract problem has no solution, neither has the concrete one.





- Abstractions can create spurious solution.
  - A solution that only works for the subtract problem.







### FTFX STFX

### **Abstraction transformation**

- Abstractions can create spurious solution.
  - A solution that only works for the subtract problem.
- How to avoid it?
  - Designing of an abstract-and-refine algorithm
    - Refine the abstract solution to make consistent with the concrete problem
  - Creating a database that stores the distances/costs from abstract states to abstract goal states.
    - Using the database to guide the search, but not using it as a solution.



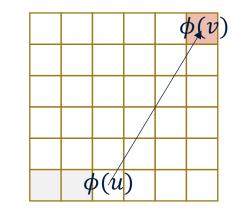
StfX

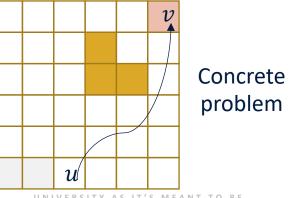
- Al Researchers try to use abstraction transformation to create admissible heuristics automatically.
- Definition (Abstraction transformation):
  - An abstraction transformation φ: S → S' maps state u in the concrete problem space to abstract states φ(u) and concrete actions a to abstract actions φ(a).



- Definition (Abstraction transformation):
  - An abstraction transformation φ: S → S' maps state u in the concrete problem space to abstract states φ(u) and concrete actions a to abstract actions φ(a).
- The distance in the abstract state space is an admissible heuristics:
  - If the distance between all states u, v ∈ S is greater or equal to the distance between all states φ(u) and φ(v).

Simplified version







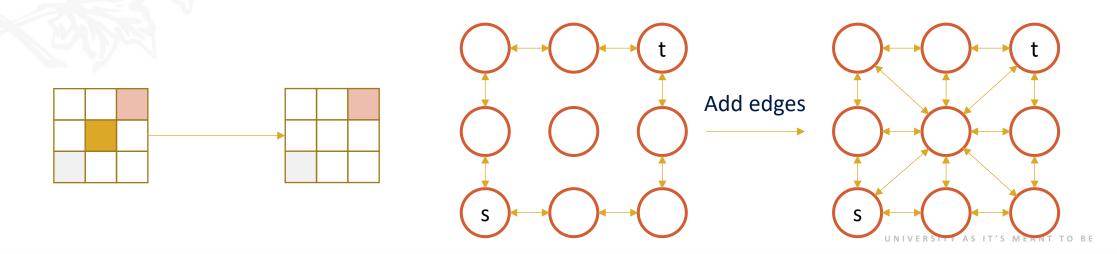
- Two ways to calculate the heuristics:
  - On demand (on the fly) like hierarchical A\*.
  - Precompute and store the goal distances (pattern databases).
- It comes back to the origin of heuristics.
  - Heuristics are a relaxations of constraints of the problem.
  - Solves the relaxed problem exactly.

### **Relaxing constraints**

- How can we relax the constraints of a problem?
  - Adding new edges
  - Merging nodes
  - Or both

#### And removing edges?

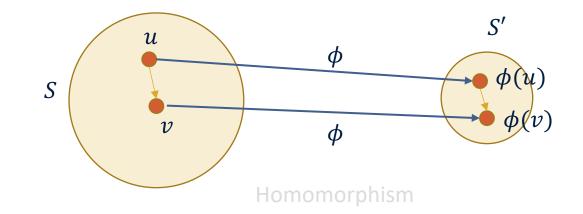
• Example



- There are two types of abstraction transformations:
  - Embedding transformation
  - Homomorphism transformation
- Definition (Embedding and Homomorphism):
  - An abstraction transformation  $\phi$  is an embedding transformation if it adds edges to S such that the concrete and abstract state sets are the same; that is,  $\phi(u) = u$  for all  $u \in S$ . Homomorphism requires that for all edges  $(u, v) \in S$ , there must also be an edge  $(\phi(u), \phi(v)) \in S'$ .

StfX

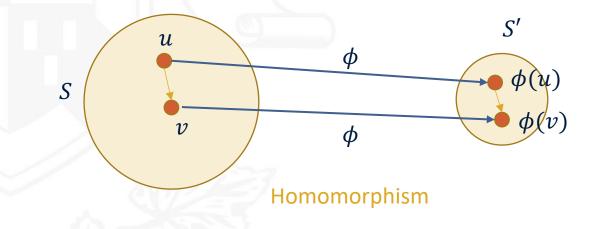
- Definition (Embedding and Homomorphism):
  - An abstraction transformation φ is an embedding transformation if it adds edges to S such that the concrete and abstract state sets are the same; that is, φ(u) = u for all u ∈ S. Homomorphism requires that for all edges (u, v) ∈ S, there must also be an edge (φ(u), φ(v)) ∈ S'.
- Embedding transformation is a special case of homomorphism.



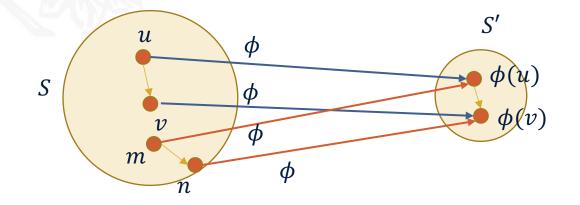
How can homomorphism hold when you reduce the state space?







How can homomorphism hold when you reduce the state space?



Several state in *S* can be map to the same abstract state in *S*'

StFX

- We made our abstraction transformation.
- We want to use the abstract state space as a heuristic.
- Is the heuristic admissible and consistent?

It depends!



### **STFX**

### Abstraction

- Definition (Admissibility and Consistency of Abstraction Heuristics):
  - Let S be a state space and  $S' = \phi(S)$  be any homomorphic abstraction transformation of S.
  - Let heuristic function  $h_{\phi}(u)$  for state u and goal t be defined as the length of the shortest path from  $\phi(u)$  to  $\phi(t)$  in S'.
  - Then  $h_{\phi}$  is an admissible, consistent heuristic function.



#### • Proof:

- If  $p = (u = u_1, ..., u_k = t)$  the shortest path in S.
- A solution in S',  $(u_1)$ , ...,  $\phi(t)$ , cannot be shorter than the optimal solution in S'.
- Recall than a heuristic h is consistent if  $h(u) \leq \delta(u, v) + h(v)$ .
- Because  $\delta_{\phi}(u, t)$  is the length of the shortest path between  $\phi(u)$  and  $\phi(t)$ .
- Then,  $\delta_{\phi}(u, t) \leq \delta_{\phi}(u, v) + \delta_{\phi}(v, t)$  for all u and v.
- Substituting  $h_{\phi}$ ,  $h_{\phi}(u) \leq \delta_{\phi}(u, v) + h_{\phi}(v')$ .
- Because  $\phi$  is an abstraction,  $\delta_{\phi}(u, v) \leq \delta(u, v)$ , therefore,  $h_{\phi}(u) \leq \delta(u, v) + h_{\phi}(v) \blacksquare$

### **Other types of abstraction transformation**

• **STAR** abstractions:

- Groups states by neighborhood.
- Starting with a state *u* with the maximum number of neighbors, an abstract state is constructed of which the range consists of all the states reachable from *u* within a fixed number of edges.
- **Domain** abstractions:
  - A domain abstraction is a mapping of labels  $\phi: L \rightarrow L'$
  - The abstract space consist of all states reachable from φ(s) by applying sequences of abstract actions.



### **Exercise**

- Find an abstraction for the following problem.
  - Draw the abstract state space graph
  - Show that it is a homomorphism abstraction transformation

